## QUANTUM GROUPS AND KNOT THEORY LECTURE: WEEK 41

This week we discuss braided Hopf algebras and braided monoidal categories. See [2, Chapter 2, sections 3 and 4].

## 1. BRAIDED MONOIDAL CATEGORIES, BRAIDED BI-ALGEBRAS AND HOPF ALGEBRAS

1. Bi-algebras and monoidal categories. Let k be a field and let A be a k-algebra. Recall that an A-module is an ordered pair (V, m) where V is a k-vector space and  $m : A \to \operatorname{End}_k(V)$  is a homomorphism of k-algebras. Often we do not write the homomorphism m explicitly, so we simple speak of the A-module V. Given an A-module V we define a "scalar multiplication" map  $\mu : A \otimes V \to V$  by  $\mu(a \otimes v) := m(a)(v)$ . It is common to use the shorthand notation  $av := \mu(a \otimes v)$ . Notice that 1v = v for all  $v \in V$ , and a(bv) = (ab)v for all  $a, b \in A$  and  $v \in V$ . Conversely, if we are given a linear map  $\mu : A \otimes V \to V$  such that 1v = v for all  $v \in V$  and also a(bv) = (ab)v for all  $a, b \in A$  and  $v \in V$  then (V, m), with  $m : A \to \operatorname{End}_k(V)$  defined by  $m(a)(v) = \mu(a \otimes v) = av$ , is an A-module.

If V, W are A-modules and  $f: V \to W$  is a k-linear map then we say that f is A-linear (notation  $f \in \text{End}_A(V, W)$ ) if f(av) = af(v) for all  $a \in A$ . Alternatively we say that f is a homomorphism of A-modules. For example the identity map  $id_V$  is always an A-linear map if V is an A-module.

Let  $\mathbf{Mod}_A$  denote the category of A-modules, i.e. the category whose objects are A-modules and whose morphisms are A-linear maps between A-modules. Let  $\mathbf{Mod}_A^f$  be the full subcategory whose objects are the A-modules which are finite dimensional as a k-vector space.

We denote  $\mathbf{Mod}_k$  by  $\mathbf{Vect}_k$ ; recall that we have equipped this category with a (nonstrict) monoidal structure with tensor unit k (see week 40). Recall the notion of a bi-algebra from week 40 (in particular week 40, Theorem 2.16):

**Theorem 1.1.** Let A be a bi-algebra over a field k. The category  $\operatorname{Mod}_A$  is a monoidal subcategory of the monoidal category  $\operatorname{Vect}_k$ . Here the tensor unit  $k = (k, \epsilon)$  is equipped with the A-module structure obtained from the counit  $\epsilon : A \to k$ , and if  $V, W \in \operatorname{Mod}_A$  then the A-action on  $V \otimes W$  is defined by

(1.1) 
$$a(v \otimes w) = \Delta(a)(v \otimes w) = \sum_{(a)} a'v \otimes a''w$$

The converse is also true: if  $\mathbf{Mod}_A$  is a monoidal subcategory of  $\mathbf{Vect}_{\mathbf{k}}$  then there exists a unique bi-algebra structure on A such that the monoidal structure of  $\mathbf{Mod}_A$  arises from the bi-algebra structure of A (but we will largely ignore this and similar "converse statements" in this syllabus).

## 2. Braidings.

2.1. Braided monoidal categories. We refer to the textbook [2, Chapter 2, section 3].

2.2. Braided Hopf algebras. Now let us assume in addition that our Hopf algebra A is braided and has an *invertible* antipode S. Braided means that A has a universal R-matrix, i.e. an invertible element  $R \in A \otimes A$  such that for all  $a \in A$  we have

(2.1) 
$$\Delta^{op}(a) = R\Delta(a)R^{-1}$$

and such that R satisfies the braiding axioms

(2.2) 
$$(\Delta \otimes \mathrm{id}_A)(R) = R_{1,3}R_{2,3}$$

(2.3) 
$$(\mathrm{id}_A \otimes \Delta)(R) = R_{1,3}R_{1,2}$$

Let us write  $R = \sum_{i} s_i \otimes t_i$ . Then the braiding relations take the following form in the Sweedler notation:

(2.4) 
$$\sum_{i} \Delta(s_i) \otimes t_i = \sum_{i,(s_i)} s'_i \otimes s''_i \otimes t_i = \sum_{i,j} s_i \otimes s_j \otimes t_i t_j$$

(2.5) 
$$\sum_{i} s_{i} \otimes \Delta(t_{i}) = \sum_{i,(t_{i})} s_{i} \otimes t'_{i} \otimes t''_{i} = \sum_{i,j} s_{i}s_{j} \otimes t_{j} \otimes t_{i}$$

Recall [2, Proposition 4.2, Ch. 2]:

**Proposition 2.2.** If A is a braided Hopf algebra with invertible antipode S then

- (a)  $R_{1,2}R_{1,3}R_{2,3} = R_{2,3}R_{1,3}R_{1,2}$ .
- (b)  $(\epsilon \otimes id_A)(R) = 1 = (id_A \otimes \epsilon)(R).$
- (c)  $(S \otimes \operatorname{id}_A)(R) = R^{-1} = (\operatorname{id}_A \otimes S^{-1})(R).$
- (d)  $R = (S \otimes S)(R)$ .

*Proof.* (a): We compute

$$R_{1,2}R_{1,3}R_{2,3} = R_{1,2}(\Delta \otimes \operatorname{id}_A)(R)$$
  
=  $(\Delta^{op} \otimes \operatorname{id}_A)(R)R_{1,2}$   
=  $(\tau \otimes \operatorname{id}_A)(\Delta \otimes \operatorname{id}_A)(R)R_{1,2}$   
=  $(\tau \otimes \operatorname{id}_A)(R_{1,3}R_{2,3})R_{1,2}$   
=  $R_{2,3}R_{1,3}R_{1,2}$ 

where  $\tau$  denotes the flip of the two tensor legs involved.

(b): We have by the co-unit axiom:

$$R = (\epsilon \otimes \mathrm{id}_A \otimes \mathrm{id}_A)(\Delta \otimes \mathrm{id}_A)(R)$$
  
=  $(\epsilon \otimes \mathrm{id}_A \otimes \mathrm{id}_A)(R_{1,3}R_{2,3})$   
=  $(\epsilon \otimes \mathrm{id}_A \otimes \mathrm{id}_A)(R_{1,3})(\epsilon \otimes \mathrm{id}_A \otimes \mathrm{id}_A)(R_{2,3})$   
=  $(1 \otimes (\epsilon \otimes \mathrm{id}_A)(R))R$ 

and since R is invertible this implies that  $(\epsilon \otimes id_A)(R) = 1$ . The other identity has a similar proof (left to the reader).

(c): By (b) and the definition of the antipode:

$$1 \otimes 1 = (\mu \otimes \mathrm{id}_A)(S \otimes \mathrm{id}_A \otimes \mathrm{id}_A)(\Delta \otimes \mathrm{id}_A)(R)$$
$$= (\mu \otimes \mathrm{id}_A)(S \otimes \mathrm{id}_A \otimes \mathrm{id}_A)(R_{1,3}R_{2,3})$$
$$= (S \otimes \mathrm{id}_A)(R)R$$

hence the invertibility of R implies the result.

Similarly we have

$$1 \otimes 1 = (\mathrm{id}_A \otimes \mu)(\mathrm{id}_A \otimes \mathrm{id}_A \otimes S^{-1})(\mathrm{id}_A \otimes \Delta^{op})(R)$$
  
=  $(\mathrm{id}_A \otimes \mu)(\mathrm{id}_A \otimes \mathrm{id}_A \otimes S^{-1})(R_{1,2}R_{1,3})$   
=  $R(\mathrm{id}_A \otimes S^{-1})(R)$ 

proving the second identity.

(d): We combine the two identities of (c):

$$(S \otimes S)(R) = (\mathrm{id}_A \otimes S)(S \otimes \mathrm{id}_A)(R)$$
$$= (\mathrm{id}_A \otimes S)(R^{-1})$$
$$= (\mathrm{id}_A \otimes S)(\mathrm{id}_A \otimes S^{-1})(R)$$
$$= R$$

2.3. The braiding of  $\mathbf{Mod}_A$ . Let A be a braided Hopf algebra with universal R-matrix R. For  $V, W \in \mathbf{Mod}_A$  we define k-linear maps

$$c_{V,W}: V \otimes W \to W \otimes V$$
$$v \otimes w \to \tau(R(v \otimes w))$$

Here  $\tau$  denotes the flip of the two tensor legs as usual, and the action of  $A \otimes A$  on  $V \otimes W$  is defined by  $(a \otimes b)(v \otimes w) = av \otimes bw$ .

**Proposition 2.3.** The k-linear maps  $c_{V,W}$  are A-linear isomorphims. The family  $c_{V,W}$  defines a commutativity constraint on  $\mathbf{Mod}_A$ . In other words, c is a natural family of A-module isomorphisms in the sense that for any two A-module morphisms  $f: V \to X$  and  $g: W \to Y$  we have

$$(2.6) (g \otimes f)c_{V,W} = c_{X,Y}(f \otimes g)$$

*Proof.* Let us check the A-linearity:

$$c_{V,W}(a(v \otimes w)) = c_{V,W}(\Delta(a)(v \otimes w))$$
  
=  $\tau(R\Delta(a)(v \otimes w))$   
=  $\tau(\Delta^{op}(a)R(v \otimes w))$   
=  $\Delta(a)\tau(R(v \otimes w))$   
=  $ac_{V,W}(v \otimes w)$ 

Because R is invertible it is clear that  $c_{V,W}$  is an isomorphism. Finally we need to show the naturality:

$$(g \otimes f)c_{V,W}(v \otimes w) = (g \otimes f)\tau(R(v \otimes w))$$
$$= \tau((f \otimes g)(R(v \otimes w)))$$
$$= \tau(R(f(v) \otimes g(w)))$$
$$= c_{X,Y}(f(v) \otimes g(w))$$

**Theorem 2.4.** The commutativity constraint c is a braiding of  $Mod_A$ .

*Proof.* In a strict monoidal category we need to show the following identities:

$$c_{U,V\otimes W} = (\mathrm{id}_V \otimes c_{U,W})(c_{U,V} \otimes \mathrm{id}_W)$$
$$c_{U\otimes V,W} = (c_{U,W} \otimes \mathrm{id}_V)(\mathrm{id}_U \otimes c_{V,W})$$

In the situation at hand we need to adapt these identities by inserting associativity constraints (as before, this can be done in a unique way). Let us write  $R = \sum_i s_i \otimes t_i$ . Observe that the braiding axioms imply that

(2.7) 
$$\sum_{i,(t_i)} s_i \otimes t'_i \otimes t''_i = \sum_{i,j} s_i s_j \otimes t_j \otimes t_i$$

Using this equality we have

$$a_{V,W,U}^{-1}(\mathrm{id}_{V}\otimes c_{U,W})a_{V,U,W}(c_{U,V}\otimes \mathrm{id}_{W})a_{U,V,W}^{-1}(u\otimes (v\otimes w))$$

$$=\sum_{i,j}(t_{i}v\otimes t_{j}w)\otimes s_{j}s_{i}u$$

$$=\tau_{U,V\otimes W}(\sum_{i,j}s_{j}s_{i}u\otimes (t_{i}v\otimes t_{j}w))$$

$$=\tau_{U,V\otimes W}(\sum_{i}s_{i}u\otimes (t_{i}'v\otimes t_{i}''w))$$

$$=\tau_{U,V\otimes W}(R(u\otimes (v\otimes w))$$

$$=c_{U,V\otimes W}(u\otimes (v\otimes w))$$

The other braiding identity is handled in a similar fashion.

**Exercise (a).** See [2, Chapter 2, Section 4.4, Exercise (a)].

**Exercise (b).** See [2, Chapter 2, Section 4.4, Exercise (b)].

2.4. The square of the antipode. Let A be a braided (or quasi triangular) Hopf algebra with invertible antipode S and universal R-matrix  $R = \sum_{i} s_i \otimes t_i$ . We define

(2.8) 
$$u := \sum_{i} S(t_i) s_i \in A$$

**Theorem 2.5.** (see [1, Proposition VIII.4.1]) The element u is invertible with inverse

(2.9) 
$$u^{-1} = \sum_{i} S^{-1}(t_i) S(s_i)$$

The square of the antipode is the inner automorphism of A obtained by conjugating with u: we have  $S^2(a) = uau^{-1}$  for all  $a \in A$ .

*Proof.* We first show that  $S^2(a)u = ua$  for all  $a \in A$ . Using the commutativity constraint we have:

(2.10) 
$$\sum_{i,(a)} s_i a' \otimes t_i a'' \otimes a''' = \sum_{i,(a)} a'' s_i \otimes a' t_i \otimes a'''$$

We apply to this identity the linear map  $A \otimes A \otimes A \to A$  defined by  $(a \otimes b \otimes c) \to S^2(c)S(b)a$  to obtain:

(2.11) 
$$\sum_{i,(a)} S^2(a''') S(t_i a'') s_i a' = \sum_{i,(a)} S^2(a''') S(a' t_i) a'' s_i$$

or

(2.12) 
$$\sum_{i,(a)} S(a''S(a'''))S(t_i)s_ia' = \sum_{i,(a)} S^2(a''')S(t_i)S(a')a''s_i$$

Using the defining property of S this gives

(2.13) 
$$\sum_{i,(a)} S(\epsilon(a'')1)S(t_i)s_i a' = \sum_{i,(a)} S^2(a'')S(t_i)\epsilon(a')s_i$$

and by co-unitality and the fact that S is an anti-algebra isomorphism we get

(2.14) 
$$\sum_{i} S(t_i)s_i a = \sum_{i} S^2(a)S(t_i)s_i$$

or  $S^2(a)u = ua$ . It remains to show that u is invertible. Let  $R^{-1} = \sum_i x_i \otimes y_i$  and put  $v = \sum_i S^{-1}(y_i)x_i$ . Then

$$uv = \sum_{i} uS^{-1}(y_i)x_i = \sum_{i} S(y_i)ux_i$$
  
=  $\sum_{i,j} S(y_i)S(t_j)s_jx_i = \sum_{i,j} S(t_jy_i)s_jx_i = 1$ 

where the last equality follows from the observation that  $1 \otimes 1 = RR^{-1} = \sum_{i,j} s_j x_i \otimes t_j y_i$ . Now apply the linear map  $A \otimes A \to A$  defined by  $a \otimes b \to S(b)a$  to this identity. Finally we use  $R^{-1} = (S \otimes id_A)(R)$  to obtain the explicit expression for  $u^{-1}$ . 

**Corollary 2.6.** The element D = uS(u) = S(u)u is central in A.

*Proof.* For all  $a \in A$  we have  $uS^{-1}(a) = S(a)u$ . Now apply S to this identity to get  $aS(u) = S(u)S^{2}(a)$ . By the previous theorem we have  $aS(u) = S(u)uau^{-1}$ , or a(S(u)u) =(S(u)u)a. Thus S(u)u is central. In particular,  $S(u)u = u(S(u)u)u^{-1} = uS(u)$ , as was claimed.  $\square$ 

The element u and the central element D play an important role in the theory of ribbon algebras. We discuss some useful properties of these elements:

**Proposition 2.7.** (see [1, Proposition VIII.4.5]).

(a)  $\epsilon(u) = 1$ . (b)  $\Delta(u) = (R_{2,1}R)^{-1}(u \otimes u) = (u \otimes u)(R_{2,1}R)^{-1}.$ (c)  $\Delta(S(u)) = (R_{2,1}R)^{-1}(S(u) \otimes S(u)) = (S(u) \otimes S(u))(R_{2,1}R)^{-1}.$ (d)  $\Delta(D) = (R_{2,1}R)^{-2}(D \otimes D) = (D \otimes D)(R_{2,1}R)^{-2}.$ 

*Proof.* (a): By Proposition 2.2(b) it follows that

$$\epsilon(u) = \sum_{i} \epsilon(S(t_i))\epsilon(s_i) = \sum_{i} \epsilon(t_i)\epsilon(s_i)$$
$$= \epsilon(\sum_{i} \epsilon(s_i)t_i) = \epsilon((\epsilon \otimes id_A)(R)) = 1$$

(b): This is a rather involved computation. We want to show that

(2.15) 
$$(R_{2,1}R)\Delta(u) = \Delta(u)(R_{2,1}R) = u \otimes u$$

First observe that  $\tau$  applied to (2.1) yields the relation  $\Delta(a) = R_{2,1} \Delta^{op}(a) R_{2,1}^{-1}$ . Hence the element  $R_{2,1}R \in A \otimes A$  commutes with  $\Delta(A)$ . This proves the first equality of (2.15). Moreover, using this property of  $R_{2,1}R$  we see that

$$\Delta(u)(R_{2,1}R) = \sum_{i} \Delta(S(t_i))\Delta(s_i)R_{2,1}R$$
$$= \sum_{i} (S \otimes S)(\Delta^{op}(t_i))\Delta(s_i)R_{2,1}R$$
$$= \sum_{i} (S \otimes S)(\Delta^{op}(t_i))R_{2,1}R\Delta(s_i)$$

Let us define a *right* action  $\diamond$  of  $A \otimes A \otimes A \otimes A$  on  $A \otimes A$  as follows: If  $X, Y, Z \in A \otimes A$ we define

(2.16) 
$$X \diamond (Y \otimes Z) := (S \otimes S)(Z)XY$$

(this is indeed a right action because  $S \otimes S$  is an anti-algebra homomorphism of  $A \otimes A$ ). Then it is clear that we can rewrite the preceding expression for  $\Delta(u)(R_{2,1}R)$  in terms of this action as follows:

(2.17) 
$$\Delta(u)(R_{2,1}R) = R_{2,1} \diamond (R_{1,2}(\Delta \otimes \Delta^{op})(R))$$

First we compute  $(\Delta \otimes \Delta^{op})(R)$  using (2.4),(2.5):

$$(\Delta \otimes \Delta^{op})(R) = (\Delta \otimes \mathrm{id}_{A \otimes A})\tau_{2,3}(\sum_{i} s_i \otimes \Delta(t_i))$$
$$= (\Delta \otimes \mathrm{id}_{A \otimes A})(\sum_{i,j} s_i s_j \otimes t_i \otimes t_j)$$
$$= \sum_{i,j} \Delta(s_i)\Delta(s_j) \otimes t_i \otimes t_j$$
$$= \sum_{i,j,k,l} s_i s_j \otimes s_k s_l \otimes t_i t_k \otimes t_j t_l$$
$$= R_{1,3}R_{1,4}R_{2,3}R_{2,4}$$
$$= R_{1,3}R_{1,4}R_{2,4}$$

Next we list some useful identities for the diamond operation. These are simple reformulations of Proposition 2.2 and of the definition of the element u:

$$((a \otimes 1)R) \diamond R_{1,4} = a \otimes 1 \ \forall a \in A$$
$$((1 \otimes b)R_{2,1}) \diamond R_{2,3} = 1 \otimes b \ \forall b \in A$$
$$(1 \otimes b) \diamond R_{1,3} = u \otimes b \ \forall b \in A$$
$$(a \otimes 1) \diamond R_{2,4} = a \otimes u \ \forall a \in A$$

For instance, the first of these is proved as follows using Proposition 2.2(c):

$$((a \otimes 1)R) \diamond R_{1,4} = \sum_{i,j} as_i s_j \otimes S(t_j) t_i$$
$$= (\mathrm{id}_A \otimes S) (\sum_{i,j} as_i s_j \otimes S^{-1}(t_i) t_j)$$
$$= (\mathrm{id}_A \otimes S) (a \otimes 1)$$
$$= a \otimes 1$$

and the others have similar proofs. Using all this we compute:

$$\begin{aligned} \Delta(u)(R_{2,1}R) &= \sum_{i} (S \otimes S)(\Delta^{op}(t_i))R_{2,1}R\Delta(s_i) \\ &= R_{2,1} \diamond (R_{1,2}(\Delta \otimes \Delta^{op})(R)) \\ &= R_{2,1} \diamond (R_{1,2}R_{1,3}R_{2,3}R_{1,4}R_{2,4}) \\ &= R_{2,1} \diamond (R_{2,3}R_{1,3}R_{1,2}R_{1,4}R_{2,4}) \\ &= (R_{2,1} \diamond R_{2,3}) \diamond (R_{1,3}R_{1,2}R_{1,4}R_{2,4}) \\ &= (1 \otimes 1) \diamond (R_{1,3}R_{1,2}R_{1,4}R_{2,4}) \\ &= (u \otimes 1) \diamond (R_{1,2}R_{1,4}R_{2,4}) \\ &= ((u \otimes 1)R) \diamond (R_{1,4}R_{2,4}) \\ &= (u \otimes 1) \diamond R_{2,4} \\ &= u \otimes u \end{aligned}$$

which is what we had set out to prove.

(c): Using that  $S : A \to A^{op,coop}$  is a bi-algebra homomorphism and using Proposition 2.2(d) we see that this identity arises from the preceding one by applying  $\tau \circ (S \otimes S)$ :

$$S(u) \otimes S(u) = \tau((S \otimes S)(u \otimes u))$$
  
=  $\tau((S \otimes S)(R_{2,1}R)\Delta(u))$   
=  $\tau(\Delta^{op}(S(u))(S \otimes S)(R)(S \otimes S)(R_{2,1}))$   
=  $\tau(\Delta^{op}(S(u))(RR_{2,1}))$   
=  $\Delta(S(u))(R_{2,1}R)$ 

(d): Take the product of identities (b) and (c).

## References

- [1] C. Kassel, *Quantum groups*, Springer GTM 155 (1995)
- [2] C. Kassel, M. Rosso, and V. Turaev, Quantum groups and knot invariants, Panoramas et syntheses 5, Soc. Math. de France (1997)